

INVERTERS AND INVERTER-BASED RESOURCES (IBRS)



INVERTERS AND IBRS

Enable grid connection of DC sources by converting DC to AC (and, for battery systems, AC to DC)



| | Synchronous machine | Inverter (non HVDC) |
|------------|---------------------|----------------------|
| Technology | Mechanical | Electronic |
| Size | Up to 100's MWs | Up to MWs |
| Source | Gas, steam, hydro | Wind, solar, battery |

- Inverter-based resources (IBRs)
 - "A source of electric power that is connected to the electric power system, and that consists of one or more IBR Unit(s) operated as a single resource at a common point of interconnection." (NERC Definition)
 - Includes, e.g., solar PV; battery energy storage system (BESS);
 wind (type III, induction, and IV, full converter)



GRID OPERATION WITH IBRS



KEY CONCEPTS

- Reliability
 - Keeping the lights on (minimize frequency and duration of outages)
- Adequacy
 - Ensuring there is enough generation
- Stability
 - Maintain operation through disturbances (keep frequency and voltage within limits)
- Protection
 - Prevent damage to systems, equipment and people

Recovery following a complete collapse is followed by a black start.

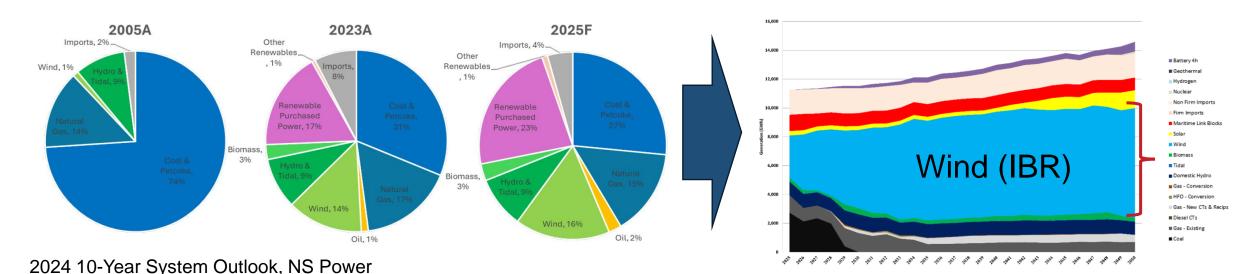
Many provinces have never had to perform a complete black start.

Where **IB**Rs have significant technical impact



EVOLUTION OF IBRS ON THE GRID

- Conventional grid architecture built around synchronous machines; ingrained in the design as reflected by, e.g., operations and protection
- Decarbonization and electrification → more renewables, more loads



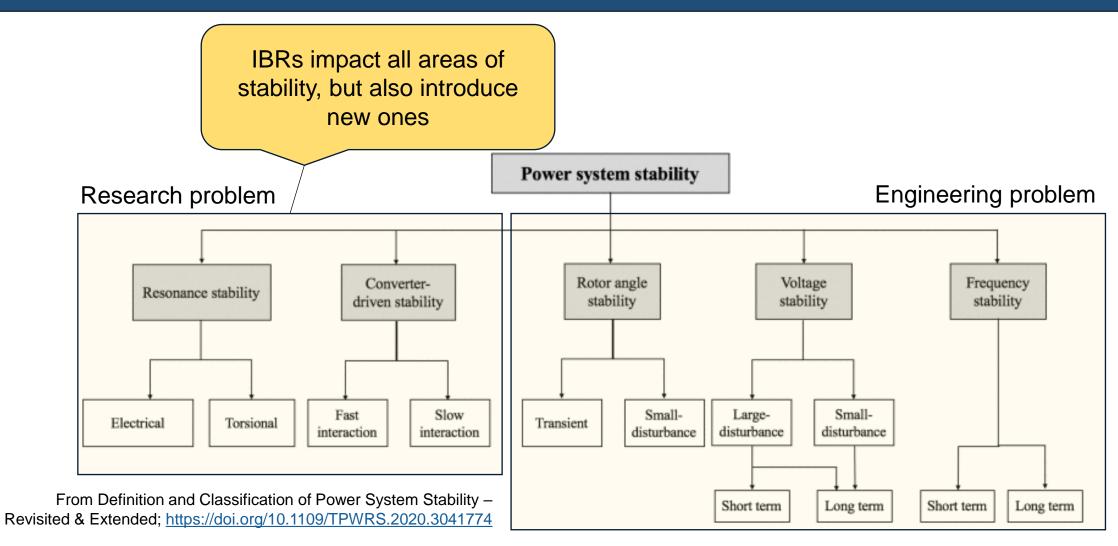
Evergreen-IRP-Update-to-IRP-Action-Plan-and-Roadmap-2023, NS Power

It's about power!





STABILITY

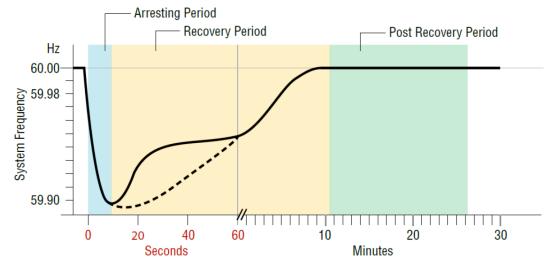






STABILITY AND PROTECTION CONCEPTS

- Frequency stability
 - Inertia (MW-s)
 - Resistance to change in movement
 - Rate of change of frequency (RoCoF, Hz/s)
 - Primary frequency response



White Paper: Fast Frequency Response Concepts and Bulk Power System Reliability Needs, NERC 2020

- Voltage stability
 - Short-circuit ratio | system strength
 - Ride-through
 - Reactive power support
 - Fault current contribution
- Protection
 - Fault current contribution





SMART INVERTERS



EVOLUTION OF INVERTERS

- Since the 90's, inverters have evolved to offer larger sets of grid support functions (capabilities)
- (Basic) inverters (outdated)
- Smart inverters
 - Grid following (GFL) ✓ (current)
 - Grid forming (GFM) (in development/early commercialization)
- Complete set of IBR capabilities (grid support functions) depends on the source and inverter
 - Adoption of GFM will probably come first with batteries





EVOLUTION OF INVERTERS II

Grid-following

- Delivers power by controlling its current and phase angle
- Relies on grid synchronization for operation, i.e., follows the grid
- · Can provide limited set of grid support capabilities
- Mature



Grid-forming, stand-alone

- Deliver power by controlling its voltage and frequency
- Can create its own waveform, but only in isolation from other grid forming equipment (e.g., single battery system in a microgrid)
- Mature



Grid-forming, interconnected

- Deliver power by controlling its **voltage** and frequency
- Can work in conjunction with other grid forming equipment while making its waveform
- In development/early commercialization





GFM VS GFL - CAPABILITIES

| | GFL | GFM |
|---|-----|---------------------------------------|
| Normal | | |
| Dispatchable* | Yes | Yes |
| Reactive power support* | Yes | Yes |
| Disturbance | | |
| Droop Primary frequency response* | Yes | Yes |
| Fast frequency response, incl. virtual inertia* | Yes | Yes, more control (emulation) options |
| Ride-through | Yes | Yes, under expanded conditions |
| Black start support | No | Yes |

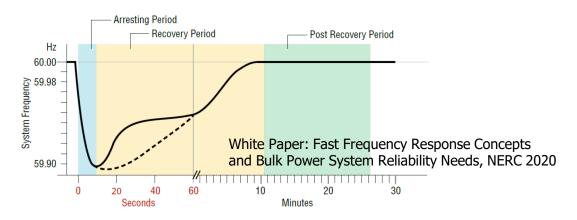
^{*} May require headroom



Canada

STABILITY AND PROTECTION CONCEPTS REVISITED

- Frequency stability
 - Inertia (MW-s)
 - Primary frequency response



| | GFL | GFM |
|-------|-----|-------|
| 1 & 2 | Ok | Great |

- Voltage stability
 - Ride-through
 - Fault current contribution
- Protection
 - Fault current contribution

| GFL | | GFM | |
|-----|---------|--|--|
| 3 | Ok | Better (before current contribution limit) | |
| 4 | Limited | Limited | |
| 5 | Limited | Limited | |







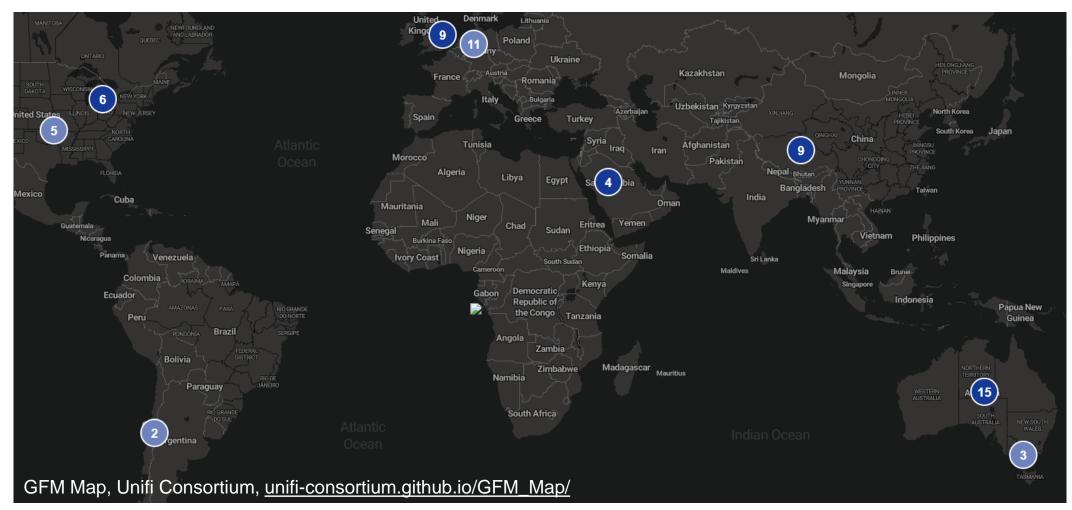


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SOLUTIONS AND REAL-WORLD EXAMPLES



STATE OF GFM IMPLEMENTATION









TOOLS TO ADDRESS SELECT NEEDS

- Low Inertia / frequency stability
 - Interconnections
 - Synchronous condensers with flywheels
 - Inverter virtual inertia via FFR
 - Curtailment
- Low short circuit contribution / voltage stability
 - Synchronous condensers
 - System reinforcement
 - Inverter ride-through

| | Stability Pathfinder Phase 1 | Stability Pathfinder Phase 2 | Stability Pathfinder Phase 3 |
|--------------------------|--|--|--|
| Requirement | Inertia and dynamic voltage GB wide | Inertia, SCL and dynamic voltage | Inertia, SCL and dynamic voltage |
| Status | All Synchronous compensators most units now live | 5 GFM BESS 5 SynComp Go-live from Apr 24 | 29 Synchronous compensators Go-live expected from 2025 |
| Participating technology | 0MW Synchronous Compensators only | Synchronous and Grid Forming Converter based | Synchronous and Grid Forming Converter based |
| Procurement regions | GB wide | Scotland | England and Wales |
| Procurement volume | 12.5 GW.s of inertia | 8.4 GVA of SCL 6 GW.s of inertia | 7.5 GVA of SCL 15 GW.s of inertia |
| Contract Detail | Up to 6 years | End of Mar 2034 | End of Mar 2035 £1.35b |
| Contract payments | Availability payments for SCL& Inertia Utilisation payments for reactive power | | |

NESO stability network services (link)





INTERCONNECTION REQUIREMENTS W/ GFM

- Ontario (IESO, <u>proposed</u>)
 - Driver: Future proofing to ensure flexibility
 - Requirement: GFM capability of BESS, but not enabled
 - Required function(s) based on NERC specifications
- UK (National Grid, <u>implemented</u>)
 - Driver: Grid service participation
 - Requirement: Optional; functional specifications
- Australia (AEMO, <u>implemented</u>)
 - Grid-forming BESS are asynchronous generating units, by definition, for the purposes of connection applications.





STATE-OF-THE-ART

- Device/System
 - Converter driven stability unknowns
 - GFM GFM
 - GFM GFL
 - GFM synchronous machine
- Standards
 - Clear requirements not yet established; awaiting functional specifications/features list
 - IEEE may fast-track Unifi requirements for GFM as a standard
- Interconnection
 - Where GFM required, should operate as GFL
 - Uncertainty how to specify in code





STATE-OF-THE-ART – TESTING

Purpose

 While electronics are the same, vendor implementation of GFM controls differ. Need to understand details from interconnection standpoint.

Activities

- Develop standard testing protocols
- Identify capabilities and minimum requirements
- Explore interoperability
- Develop specification framework

Core Organizations

- International Smart Grid Action Network (ISGAN) Working Group 5 (https://www.iea-isgan.org/our-work3/wg_5/)
- Unifi Consortium (US based) (https://unificonsortium.org/)
 - Inverter interoperability through hardware testing

NRCan's CanmetENERGY is a member of both initiatives





STATE-OF-THE-ART – MODELING

Electromagnetic Transient (EMT)

- Time domain over short period (minutes, micro-second time-steps)
- Computationally intensive
- Accuracy requires lots of detail; data not normally in public domain
- Used for analyzing stability following large disturbances
- Dynamic
 - Phasor domain (typically) over medium periods (cycle up to hourly time-steps)
 - Captures element behaviour over time
 - Used for analyzing stability following small changes in load and generation; also, economic dispatch

- How do you model GFMs? (architecture, parameterization)
- How do you "mix and match"
 power system modeling needs
 (e.g., stability, inertia, and capacity
 expansion)





THANK YOU!

QUESTIONS?





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